This listing of claims will replace all prior versions, and listings, of claims in the application:

Claim 1 (canceled)

- 1 Claim 2 (currently amended): The method of claim 64
- 2 wherein the position information includes coordinate
- 3 information.
- 1 Claim 3 (previously presented): The method of claim 6 4
- 2 wherein the position information includes change of
- 3 position information.

Claims 4 and 5 (canceled)

- 1 Claim 6 (currently amended): A method comprising:
- 2 a) capturing a plurality of image parts;
- b) determining position information corresponding to
- 4 each of the plurality of image parts; and
- c) generating image information using, at least, the
- 6 plurality of image parts and the corresponding
- 7 position information,
- wherein the act of capturing a plurality of image
- 9 parts includes focusing light reflected from a surface onto
- 10 an image pickup device,
- wherein the act of determining position information
- 12 includes accepting, by the image pickup device, light
- 13 reflected from the surface,
- 14 The method of claim 4 wherein the light reflected from the
- 15 surface is emitted from a first light source and a second
- 16 light source,

- wherein the light emitted from the first light source
- 18 and reflected from the surface onto the image pickup device
- 19 is used in the act of capturing a plurality of image parts,
- 20 and
- wherein the light emitted from the second light source
- 22 and reflected from the surface onto the image pickup device
- 23 is used in the act of determining position information.
 - 1 Claim 7 (original): The method of claim 6 wherein the
- 2 light emitted from the first light source has a larger
- 3 angle of incidence with the surface than the light emitted
- 4 from the second light source.
- 1 Claim 8 (currently amended): A method comprising:
- 2 a) capturing a plurality of image parts;
- 3 b) determining position information corresponding to
- each of the plurality of image parts; and
- 5 c) generating image information using, at least, the
- 6 plurality of image parts and the corresponding
- 7 position information,
- 8 wherein the act of capturing a plurality of image
- 9 parts includes focusing light reflected from a surface onto
- 10 a first image pickup device, and
- wherein the act of determining position information
- 12 includes focusing light reflected from the surface onto a
- 13 second image pickup device,
- wherein the light reflected from the surface is
- 15 emitted from a first light source and a second light
- 16 source,
- wherein the light emitted from the first light source
- 18 and reflected from the surface onto the first image pickup

- device is used in the act of capturing a plurality of image 19 parts, and 20 wherein the light emitted from the second light source 21 and reflected from the surface onto the second image pickup 22 device is used in the act of determining position 23 24 information. Claims 9-10 (canceled) Claim 11 (currently amended): The method of claim 8 10 1 wherein the light emitted from the first light source has a 2 larger angle of incidence with the surface than the light 3 emitted from the second light source. 4 Claim 12 (currently amended): Apparatus comprising: 1 a) means for capturing a plurality of image parts; 2 means for determining position information 3 corresponding to each of the plurality of image parts; 4
 - 6 c) means for generating image information using, at
 - 7 least, the plurality of image parts and the
 - 8 corresponding position information,
 - 9 wherein the means for capturing a plurality of image
 - 10 parts includes

and

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- 11 1) a first light source, and
- 12 2) an imaging device, and
- wherein the means for determining position information
- 14 includes a second light source.
 - 1 Claim 13 (original): The apparatus of claim 12 wherein the
 - 2 position information includes coordinate information.

- 1 Claim 14 (original): The apparatus of claim 12 wherein the
- 2 position information includes change of position
- 3 information.
- 1 Claim 15 (original): The apparatus of claim 12 wherein the
- 2 position information includes orientation information.
- 1 Claim 16 (original): The apparatus of claim 12 wherein the
- 2 position information includes acceleration information.
- 1 Claim 17 (original): The apparatus of claim 12 wherein the
- 2 position information includes velocity information

Claims 18 and 19 (canceled)

- 1 Claim 20 (original): The apparatus of claim 12 wherein the
- 2 first light source and the second light source emit light
- 3 that illuminates a surface, and
- 4 wherein the light emitted from the first light source
- 5 has a larger angle of incidence with the surface than the
- 6 light emitted from the second light source.
- 1 Claim 21 (currently amended): The apparatus of claim 12 19
- 2 wherein the second light source is a light emitting diode.
- 1 Claim 22 (currently amended): The apparatus of claim 12 19
- 2 wherein the second light source is an infra-red light
- 3 emitting diode.
- 1 Claim 23 (currently amended): The apparatus of claim 12 19
- 2 wherein the second light source is a tunable light source

- 3 able to modulate at least one of wavelength, polarization,
- 4 and amplitude.
- 1 Claim 24 (currently amended): The apparatus of claim 12
- 2 wherein the means for capturing a plurality of image parts
- 3 includes
- 4 1) a light source, and
- 5 2) a first-imaging device, and
- 6 wherein the means for determining position information
- 7 further includes
- 8 1) the light source, and
- 9 2) a second imaging device.

Claim 25 (canceled) .

- 1 Claim 26 (currently amended): The method of claim 6 4
- 2 wherein the image parts are captured from a paper document,
- 3 and
- 4 wherein the act of generating image information using,
- 5 at least, the plurality of image parts and the
- 6 corresponding position information uses the image parts to
- 7 compose a larger image.
- 1 Claim 27 (previously presented): The method of claim 8
- 2 wherein the image parts are captured from a paper document,
- 3 and
- 4 wherein the act of generating image information using,
- 5 at least, the plurality of image parts and the
- 6 corresponding position information uses the image parts to
- 7 compose a larger image.